

# ROBOT CONTROL METHOD AND ROBOT CONTROLLER APPLYING THE METHOD

**Publication number:** JP2002192486 (A)

**Publication date:** 2002-07-10

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**Classification:**

**- international:** B25J13/00; B25J9/06; B25J9/16; B25J9/18; B25J9/22; B65G47/90; G06T1/00; B25J13/00; B25J9/06; B25J9/16; B25J9/18; B25J9/22; B65G47/90; G06T1/00; (IPC1-7): B25J13/00; B25J9/06; B65G47/90; G06T1/00

**- European:** B25J9/16P4

**Application number:** JP20000392392 20001225

**Priority number(s):** JP20000392392 20001225

**Also published as:**

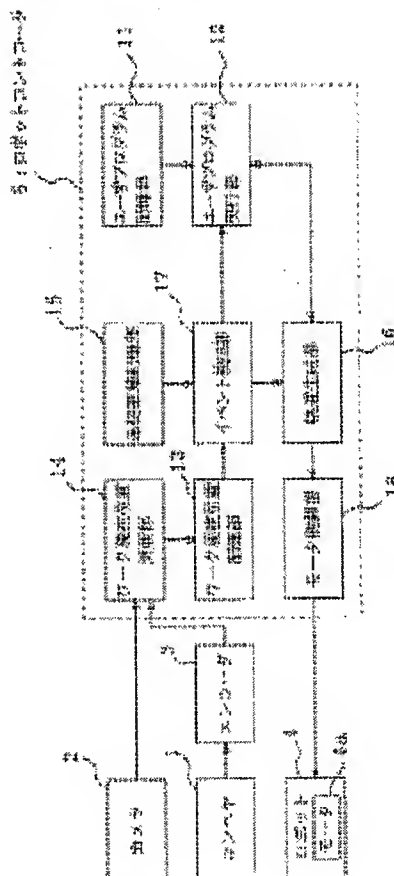
DE10162967 (A1)

US2002105296 (A1)

US6646404 (B2)

## Abstract of JP 2002192486 (A)

**PROBLEM TO BE SOLVED:** To provide a robot control method and a robot controller capable of reducing arithmetic operation quantity independent of a moving passage of a work in arithmetically operating a present position of the work with the movement of a conveyor and describing the operation and intuitively teaching relative to the work. **SOLUTION:** The present position of the work is sequentially renewed by a coordinate system of the conveyor 1 so that the trajectory of the robot 4 for following the work is generated by converting the position of the work from the coordinate system of the conveyor 1 to the coordinate system of the robot 4.



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